

Riemannian Geometry Week 11

Last time: If $N \subset (M, g)$ is a submanifold:

$\Gamma(M, N)$: Vector fields on M tangent to N .

Weingarten equation: If $X, Y \in \Gamma(M, N)$, $W \in \Gamma(M)$, $W|_p \perp T_p N \ \forall p \in N$, then

$$\langle \nabla_X W, Y \rangle = - \langle W, \underbrace{B(X, Y)}_{(\nabla_X Y)^\perp} \rangle$$

and $(\bar{\nabla}_X Y) = (\nabla_X Y)^T$
and:

Gauss equation:

$\forall X, Y, Z, W \in T_p N$:

$$\bar{R}(X, Y, Z, W) - R(X, Y, Z, W) = \langle B(X, Z), B(Y, W) \rangle - \langle B(X, W), B(Y, Z) \rangle$$

ass. to $\bar{g}$
(induced metric)

Proof: I can extend X, Y, Z, W to $\Gamma(M, N)$.

Without loss of generality: $[X, Y]|_p = 0$.

Then:

(recall: $R(X, Y, Z, W) = \langle R(X, Y)W, Z \rangle$)

$$\bar{\nabla}_X \bar{\nabla}_Y W = \nabla_X (\bar{\nabla}_Y W) - B(X, \bar{\nabla}_Y W)$$

$$= \nabla_X (\nabla_Y W) - \nabla_X (B(Y, W)) - B(X, \bar{\nabla}_Y W)$$

$$\begin{aligned} \text{So } \langle \bar{\nabla}_X \bar{\nabla}_Y W, Z \rangle &= \langle \nabla_X \nabla_Y W, Z \rangle - \langle \nabla_X (B(Y, W)), Z \rangle - \langle B(X, \bar{\nabla}_Y W), Z \rangle \\ &= \langle \nabla_X \nabla_Y W, Z \rangle + \langle B(Y, W), \nabla_X Z \rangle \\ &= \langle \nabla_X \nabla_Y W, Z \rangle + \langle B(Y, W), B(X, Z) + \text{tangent} \rangle \end{aligned}$$

Subtracting the same relation with $X \leftrightarrow Y$, I get the Gauss equation $\square$

When N is a hypersurface (i.e. codim 1), co-oriented (with ~~non~~ unit normal $\hat{n}$):

Scalar second fundamental form:

$$b(x, y) = \langle B(x, y), \hat{n} \rangle$$

Weingarten map: $X \in T_p N \rightarrow (\nabla_X \hat{n})^T \in T_p N = L(X)$

$$\text{So } b(x, y) = \langle \nabla_X Y, \hat{n} \rangle = \langle -\nabla_X \hat{n}, Y \rangle$$

$$\text{Symmetry of } b \Rightarrow \langle L(X), Y \rangle = \langle L(Y), X \rangle = -\langle \nabla_X \hat{n}, Y \rangle$$

Principal curvatures at a point p : $k_1(p), \dots, k_n(p)$:

Eigenvalues of L_p (real)

Gauss curvature:

$$K_{\text{Gauss}} = \det L = k_1 \cdots k_n$$

~~Mean curvature~~

Mean curvature: $H(p) = \frac{1}{n} \operatorname{tr} L = \frac{k_1 + \dots + k_n}{n}$

Umbilic point: $k_1 = k_2 = \dots = k_n$

If $N^2 \subset M^3$: Gauss equation: $\bar{K}(p) = K(p) + K_{\text{Gauss}}(p)$

In $\mathbb{R}^3$: ($K(p) = 0$) Gauss curvature is integrate ($= \frac{1}{2} S$)

If the hypersurface $N \subset M$ is given as the level set $\{f = \text{const}\}$ with $df|_p \neq 0$:

$$\hat{n} = \frac{\text{grad } f}{\|\text{grad } f\|} \quad (\text{grad } f)^a = g^{ap} \partial_p f$$

$$b(x, y) = - \frac{\text{Hess } f(x, y)}{\|\text{grad } f\|}$$

$$\text{Hess } f = \nabla df \quad \text{so} \quad (\text{Hess } f)_{ab} = \partial_{ab}^2 f - \Gamma_{ab}^k \partial_k f$$

In general: $b = -\frac{1}{2} \mathcal{L}_{\hat{n}} g$

Second variation formula:

We have seen that curves which ~~minimize~~ are stationary points of the length functional are geodesics. When are geodesics (locally) length minimizing?

~~We know~~ The answer to this question has topological consequences

Theorem (2nd variation formula)

Let $\gamma: [a, b] \rightarrow (M, g)$ be a geodesic parametrized by arc length ($\|\dot{\gamma}\| = 1$). Let $\phi: (-\epsilon, \epsilon) \times [a, b] \rightarrow M$ be a variation of γ ($\phi_0(t) = \gamma(t)$). Let $X = d\phi(\frac{\partial}{\partial s}) = \frac{\partial \phi}{\partial s}$ be the variation vector field.

Then

$$\left. \frac{d^2}{ds^2} l(\phi_s) \right|_{s=0} = \langle \nabla_X X, \dot{\gamma} \rangle \Big|_{t=a}^b +$$

$$+ \int_a^b (\|\nabla_{\dot{\gamma}} X\|^2 - \underbrace{R(\dot{\gamma}, X, \dot{\gamma}, X)}_{K(\dot{\gamma}, X) \|\dot{\gamma}\|^2 \|\dot{X}\|^2}) dt$$

where $\gamma^\perp = \gamma - \frac{\langle \gamma, \dot{\gamma} \rangle}{\|\dot{\gamma}\|^2} \dot{\gamma}$.

We will denote with $T = d\phi(\frac{\partial}{\partial s})$ the tangent to ϕ_s .

Lem: $\nabla_T X = \nabla_X T$

and $\langle \nabla_X \nabla_T X, T \rangle = \langle \nabla_T \nabla_X X, T \rangle - R(T, X, T, X)$

Proof: $\nabla_T X - \nabla_X T = -[T, X] = [d\phi(\frac{\partial}{\partial s}), d\phi(\frac{\partial}{\partial s})] = d\phi([\frac{\partial}{\partial s}, \frac{\partial}{\partial s}])$

And $R(X, T)X = \nabla_X \nabla_T X - \nabla_T \nabla_X X$

and $R(T, X, T, X) = \cancel{R(T, X, T, X)}$
 $- R(X, T, T, X) = \langle R(X, T)X, T \rangle$

□

Lem: For any variation:

$$\frac{d}{ds} l(\phi_s) = \int_a^b \frac{\langle \nabla_T X, T \rangle}{\|T\|} dt \quad (\text{not just at } s=0)$$

Proof: $l(\phi_s) = \int_a^b \|T\| dt = \int_a^b \sqrt{\langle T, T \rangle} dt$

$$\begin{aligned} \frac{d}{ds} l(\phi_s) &= \int_a^b \frac{d}{ds} \sqrt{\langle T, T \rangle} dt = \int_a^b \frac{1}{2} \frac{\frac{d}{ds} \langle T, T \rangle}{\sqrt{\langle T, T \rangle}} dt \\ &= \int_a^b \frac{\langle \nabla_X T, T \rangle}{\sqrt{\langle T, T \rangle}} dt \stackrel{[X, T]=0}{=} \int_a^b \frac{\langle \nabla_T X, T \rangle}{\|T\|} dt \end{aligned}$$

Lem: At $s=0$: $\|\nabla_{\dot{\gamma}} X^\perp\|^2 = \|\nabla_{\dot{\gamma}} X\|^2 - \langle \nabla_{\dot{\gamma}} X, \dot{\gamma} \rangle^2$

Proof: ~~$\nabla_{\dot{\gamma}} X^\perp = \nabla_{\dot{\gamma}} X - \langle \nabla_{\dot{\gamma}} X, \dot{\gamma} \rangle \dot{\gamma}$~~ and $(\nabla_{\dot{\gamma}} X)^\perp = \nabla_{\dot{\gamma}} (X^\perp)$

$$D_j X = (D_j X)^\perp + \underbrace{\langle D_j X, j \rangle}_{\text{orthogonal}} j$$

$$\Rightarrow \|D_j X\|^2 = \|(D_j X)^\perp\|^2 + \langle D_j X, j \rangle^2$$

$$\text{And } D_j(X^\perp) = D_j(X - \langle X, j \rangle j) = D_j X - \langle D_j X, j \rangle j = (D_j X)^\perp$$

Proof of the theorem

$$\text{Start from } \frac{d}{ds} l(\phi_i) = \int_a^b \frac{\langle D_T X, T \rangle}{\|T\|} ds$$

$$\begin{aligned} \text{Note: } \frac{\partial}{\partial s} \left(\frac{\langle D_T X, T \rangle}{\|T\|} \right) &= \frac{\frac{\partial}{\partial s} \langle D_T X, T \rangle}{\|T\|} - \langle D_T X, T \rangle \cdot \frac{\frac{\partial}{\partial s} \|T\|}{\|T\|^2} \\ &= \frac{\langle D_X D_T X, T \rangle + \langle D_T X, D_X T \rangle}{\|T\|} - \langle D_T X, T \rangle \frac{\frac{\partial}{\partial s} \|T\|}{\|T\|^2} \\ &= \frac{\langle D_T D_X X, T \rangle - R(T, X, T, X) + \|D_T X\|^2}{\|T\|} - \frac{\langle D_T X, T \rangle^2}{\|T\|^3} \end{aligned}$$

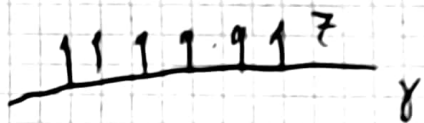
$$\text{At } s=0 \quad (\|T\|=1, T=j, D_j X=0):$$

$$\begin{aligned} \dots &= \langle D_j D_X X, j \rangle - R(j, X, j, X) + \|D_j X\|^2 - \langle D_j X, j \rangle^2 \\ &= j(\langle D_X X, j \rangle) - R(j, X, j, X) + \|D_j X^\perp\|^2 \end{aligned}$$

Integrating over $t \in [a, b]$: We obtain the required formula



Special case:



Let $\gamma: [0,1] \rightarrow M$ be a geodesic

with $\|\dot{\gamma}\|=1$

and $Z \in T_\gamma$ with $Z \perp \dot{\gamma}$, $\nabla_{\dot{\gamma}} Z = 0$

Let $\phi(t,s) = \exp_{\gamma(t)}(s \cdot f(t) \cdot Z)$



↑ Note: $\nabla_X X = 0$ ($s \mapsto \phi(t,s)$ is geodesic)

then $\frac{d}{ds} l(\phi_r) \Big|_{s=0} = \int_0^1 (\|\nabla_{\dot{\gamma}} X^\perp\| - R(\dot{\gamma}, X, \dot{\gamma}, X)) dt$

But: $X = f(t) \cdot Z$

$\Rightarrow \nabla_{\dot{\gamma}} X = f' \cdot Z$

So $\frac{d^2}{ds^2} l(\phi_r) \Big|_{s=0} = \int_0^1 ((f')^2 - K(\dot{\gamma}, Z) \cdot f^2) dt$

So: If f "oscillates" a lot: $l(\phi_r)$ increases

If $K > 0$, f almost flat: $l(\phi_r)$ decreases

(compare with the case of an equatorial circle in S^2)

Theorem (Bonnet - Myers)

Let (M, g) be a complete and connected Riem. manifold

With Ric tensor satisfying $\text{Ric} \geq a^2(n-1) > 0$, i.e. $\forall X$

$$\text{Ric}(X, X) \geq a^2(n-1) \|X\|^2$$

Then $\text{diam}(M, g) \leq \frac{\pi}{a}$ (and M is compact).

Rmk: The extreme value is attained for the sphere of ~~the~~ radius $R = \frac{1}{a}$.

Rmk: Let $\tilde{M}$ be the universal cover of $M \Rightarrow (\tilde{M}, g)$ also satisfies the above properties $\Rightarrow \tilde{M}$ is compact

$\Rightarrow \pi_1(M)$ is finite

(So: No metric with strictly positive Ricci tensor on $\mathbb{T}^n$)

Rmk: Positivity of the Ricci tensor implies topological constraints on M

But: Every M ($\dim M \geq 3$) admits metric with negative Ricci tensor (Lichamp)